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$\int_{\Omega} \dot{\mathbf{S}} : grad\delta \mathbf{v} dV - \int_{\partial \Omega} \dot{\mathbf{t}} \cdot \delta \mathbf{v} dS = 0,$ Principle of virtual work in the updated Lagrangian form	
1) $\int_{\Omega} \dot{\mathbf{S}} : \operatorname{grad} \delta \mathbf{v} dV = \int_{\Omega} [\tau : \delta \mathbf{D} - \tau : (\delta \mathbf{L}^{T} \mathbf{L} - 2 \mathbf{D} \delta \mathbf{D})] dV,$	
where $\delta \mathbf{v} = \delta \dot{\mathbf{F}} = \delta \mathbf{L}$ $\mathbf{D} = \frac{1}{2} (\mathbf{L} + \mathbf{L}^T)$. $\overset{\forall}{\boldsymbol{\tau}} = \dot{\boldsymbol{\tau}} - \mathbf{W} \boldsymbol{\tau} + \boldsymbol{\tau} \mathbf{W}$ $\mathbf{S} = \boldsymbol{\tau} \mathbf{F}^{-T}$	
2) $\dot{\mathbf{t}} = \frac{\partial \mathbf{t}}{\partial \mathbf{F}} : \dot{\mathbf{F}} = \frac{\partial \mathbf{t}}{\partial \mathbf{F}} : \mathbf{L}$ the change in intensities of the applied tractions arises due to the change in geometry	
$\int_{\Omega} \delta \mathbf{D} : \mathbb{C} : \mathbf{D} dV - \int_{\Omega} (\sigma + \lambda \Delta \sigma) : (\delta \mathbf{L}^{T} \mathbf{L} - 2 \mathbf{D} \delta \mathbf{D}) dV - \int_{\partial \Omega} \left(\frac{\partial (\mathbf{t} + \lambda \Delta \mathbf{t})}{\partial \mathbf{F}} : \mathbf{L} \right) \bullet \delta \mathbf{v} dS = 0$	0,
Finite element discretization $\left(m{K}_{0} + \lambda m{K}_{\Delta} ight) \hat{m{v}} = m{0},$	
\mathbf{K}_0 is the initial stiffness matrix which accounts for the effect of the existing stresses and tractions. \mathbf{K}_{Δ} is the differential stiffness matrix , generated by the perturbation stresses and tractions.	0



























