

# Introduction to Particle Systems and Modeling Methods

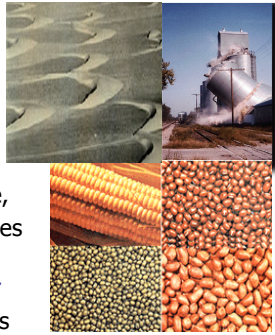
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## Granular Materials

Real:

- sand, soil, rock,
- grain, rice, lentils,
- powder, pills, granulate,
- micro- and nano-particles



*Model Granular Materials*

- steel/aluminum spheres
- spheres with **dissipation**/friction/**adhesion**

## Why Granular Materials

Numberless applications:

- constructions, industry (silos), agriculture, ...
- everyday life (e.g. coffee powder, sugar, salt, ...)

*Challenges for Physics, Mechanics, Materials- and Computational Science and Engineering*

- many particle systems, **non-linear**, **non-equilibrium**



- segregation (mixing), pattern formation
- force chains (wide distributions)
- localization (shearbands, fracture)

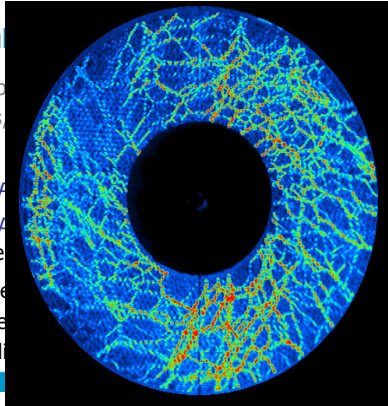
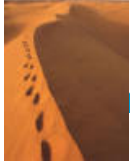
## Why Granular

Numberless applications

- constructions
- everyday life

Challenges for Physics and Computation

- many particles
- segregation
- force chains
- local order



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## Clustering

- vibrated (weak) box with compartments



Experiments:  
Twente, NL,  
D. Lohse et al. 2001, ...

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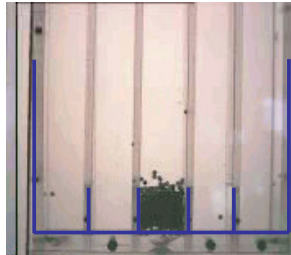
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## Clustering

- (strongly) vibrated box with compartments



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## What is the problem ?

- Excluded volume effects ... crystallization
- Granular medium with ALL densities realized
- Dissipation & Friction & Adhesion
- Out of equilibrium, chaotic
- Non-equipartition of energies
- Temperature and pressure dependence
- sintering, fracture, damage, ...
- etc.

## How to approach ?

### Experiments ...

**Continuum theory** (materials, micropolar, ...)

### Statistical Physics

+ Kinetic theory + dissipation + friction

### Numerical Modeling

- Monte Carlo (stochastic methods)
- Molecular dynamics-like simulations (MD++)
- Finite Element Method (FEM)

## Numerical Modeling Overview

### Scales and examples:

sub-particle (atomistic – molecular dynamics)  
particle & particle-contact modeling  
multi-particle modeling (discrete element method)  
system modeling (silo, reactor, ...)  
    using e.g. FEM to solve continuum theory  
process and plant modeling

### Methods discussed:

particle methods (stochastic-deterministic)  
finite element model (FEM)

### Deterministic or Stochastic Models ?

Method	Abbrev.	Theory
Molecular dynamics (soft particles)	MD	...
Event Driven (hard particles)	ED	(Kinetic Theory)
Monte Carlo (random motion)	MC	Stat. Phys.
Direct Simulation Monte Carlo	DSMC	Kinetic Theory
Lattice (Boltzmann) Models	LB	Navier Stokes




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### Deterministic or Stochastic Models ?

Method	Determ./ Stochast.	Discrete Time	Discrete Space	Discrete Events	Flexible	Fast
MD (soft p.)	D	X			*****	*
ED (hard p.)	D			X	*	***
MC	S	?			*	**
DSMC	S	X			***	****
LB	S	X	X		*	*****




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### DCCSE – steps in simulation

see:  
[pcse.tudelft.nl/index.php?page=introduction](http://pcse.tudelft.nl/index.php?page=introduction)

1. Setting up a model
2. Analytical treatment
3. Numerical treatment
4. Implementation
5. Embedding
6. Visualisation
7. Validation




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## DCCSE – steps in simulation

see:  
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- |                         |                           |
|-------------------------|---------------------------|
| 1. Setting up a model   | 1. Particle model         |
| 2. Analytical treatment | 2. Kinetic theory         |
| 3. Numerical treatment  | 3. Algorithms for MD      |
| 4. Implementation       | 4. FORTRAN or C++/MPI     |
| 5. Embedding            | 5. Linux – research codes |
| 6. Visualisation        | 6. xballs X11 C-tool      |
| 7. Validation           | 7. theory/experiment      |

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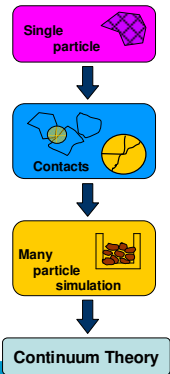
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## Approach philosophy

- Introduction
- Single Particles
- Particle Contacts/Interactions
- Many particle cooperative behavior
- Applications/Examples
- Conclusion




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## Deterministic Models ...

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## What is Molecular Dynamics ?

1. Specify interactions between bodies

2. Compute all forces

$$\mathbf{f}_{j \rightarrow i}$$

3. Integrate the equations of motion for all particles

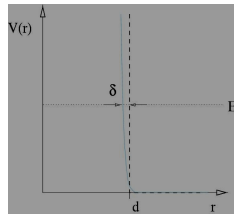
$$m\ddot{\mathbf{x}}_i = \sum_{j \neq i} \mathbf{f}_{j \rightarrow i}$$

## What is Molecular Dynamics ?

1. Specify interactions between bodies (for example: two spherical atoms)

2. Compute all forces  $\mathbf{f}_{j \rightarrow i}$

3. Integrate the equations of motion for all particles (Verlet, Runge-Kutta, Predictor-Corrector, ...) with fixed time-step  $dt$

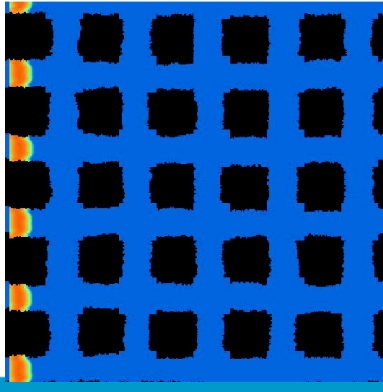


$$m\ddot{\mathbf{x}}_i = \sum_{j \neq i} \mathbf{f}_{j \rightarrow i}$$

## Applications & Examples

1. Flow in porous media (fluids)
2. Granular Flow (pipe & hopper)
3. Vibration & Segregation
4. Granular Gases (Diffusion & Clustering)
5. Shear cells (slow, dense flow)
6. Membranes (topology & fluctuations)
7. Adhesion and Sintering (attractive forces)
8. Sound propagation (wave theory)
9. Electro-spray (charged particles = long-range forces)
10. Particle-Fluid coupling

## Flow in porous media



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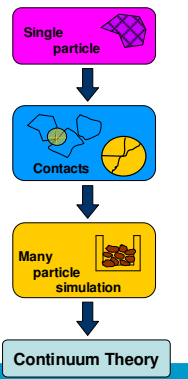
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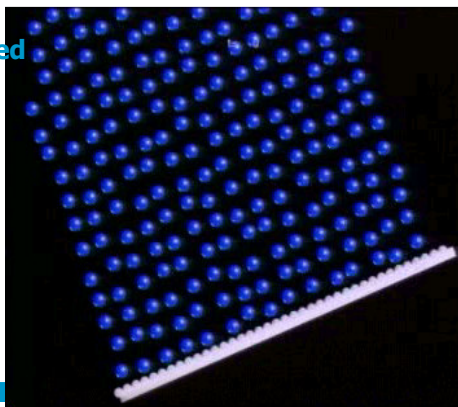
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## Inclined plane



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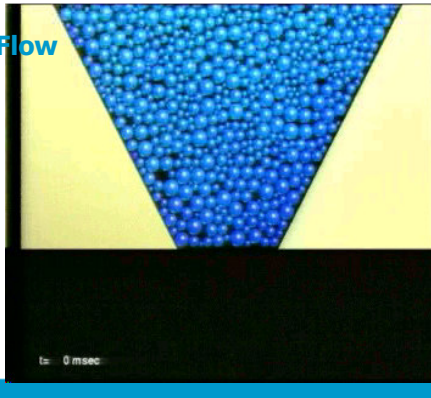
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### Hopper Flow



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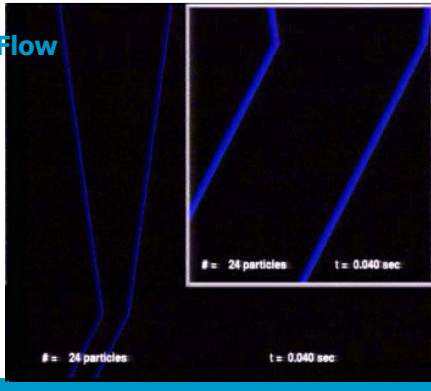
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### Hopper Flow



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### Silo Flow



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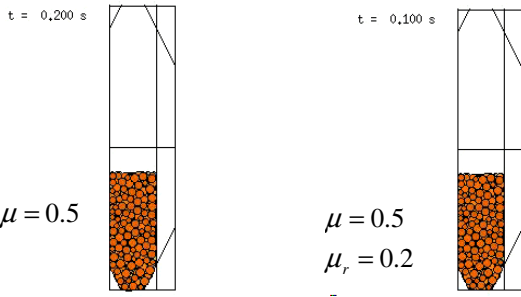
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### Silo Flow with friction



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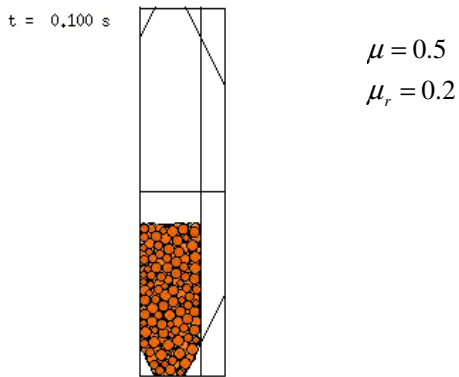
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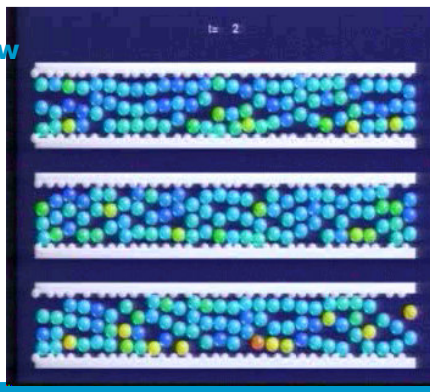
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### Pipe Flow



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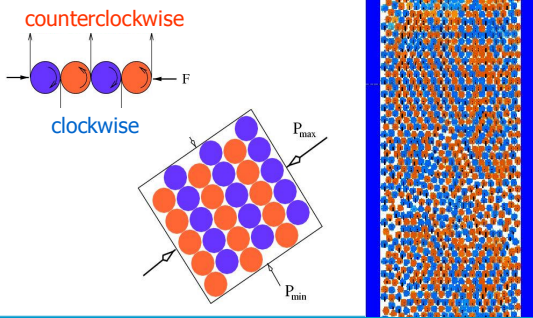
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### Rotational order



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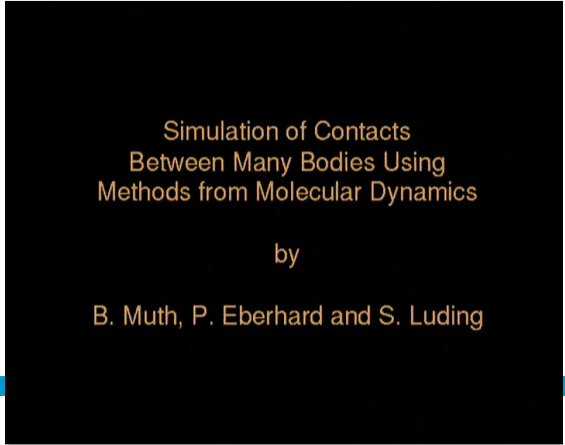
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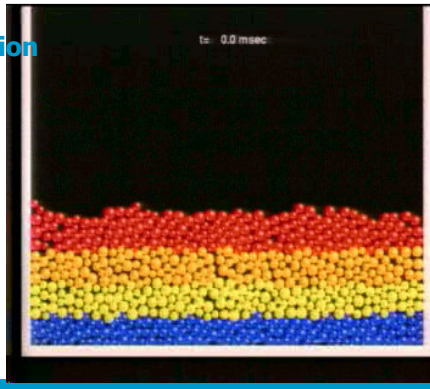
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### Convection



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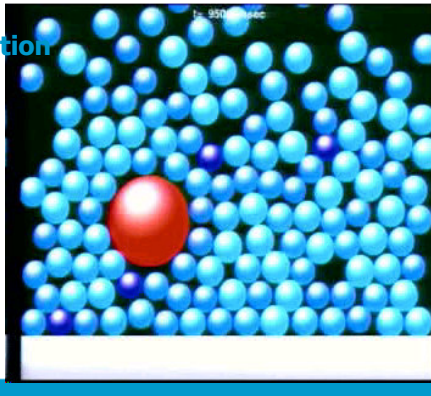
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## Segregation



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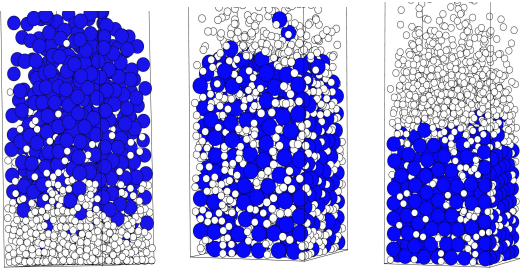
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## Segregation – Mixing – Reverse segregation



P. V. Quinn, D. Hong, SL, PRL 2001

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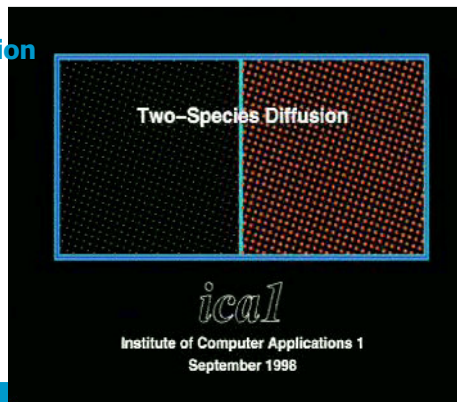
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## Diffusion



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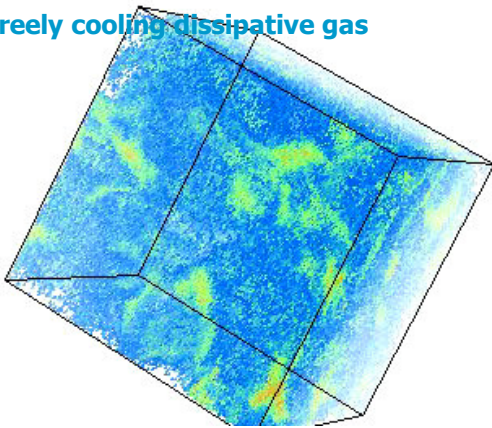
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## Cooling of a Dissipative System (ED Simulation)

$10^5$  Particles  
Restitution: 0.9  
Volume Fraction: 0.25  
Periodic Boundaries

Freely cooling dissipative gas

3D



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