



0 April 2013

Journal of Fluid Mechanics

VOLUME 720



Experimental chute setup and coordinate system

Cui & Gray J. Fluid. Mech., 720, 314-337.

Derivation of the depth-averaged equations

Mass and momentum balances

$$\nabla \cdot \boldsymbol{u} = 0$$

$$\frac{\partial}{\partial t}(\rho \boldsymbol{u}) + \nabla \cdot (\rho \boldsymbol{u} \otimes \boldsymbol{u}) = \nabla \cdot \boldsymbol{\sigma} + \rho \boldsymbol{g},$$

- assume density ρ constant
- bulk velocity $u = (u, w)^T$ and \otimes is the dyadic product
- ullet stress $oldsymbol{\sigma}$ split into a pressure p and a deviatoric part $oldsymbol{ au}$

$$\sigma = -p\mathbf{1} + \boldsymbol{\tau}$$

subject to kinematic conditions at surface and base

$$\frac{\partial z}{\partial t} + u \frac{\partial z}{\partial x} - w = 0$$
, at $z = s(x, t)$ and $z = b(x, t)$,

and surface and basal traction conditions

$$z = s(x,t)$$
: $\sigma n = 0$, $z = b(x,t)$: $\sigma n = -(u/|u|)\mu(n \cdot \sigma n) + n(n \cdot \sigma n)$,

where n is the normal and μ is the friction coefficient.

• integrate $abla \cdot u = 0$ through depth using Leibniz' Rule

$$\frac{\partial}{\partial \lambda} \int_{b(\lambda)}^{s(\lambda)} f \, dz = \int_{b(\lambda)}^{s(\lambda)} \frac{\partial f}{\partial \lambda} \, dz + \left[f \frac{\partial z}{\partial \lambda} \right]_{b(\lambda)}^{s(\lambda)},$$

• to exchange the order of integration and differentiation

$$\int_{b(x,t)}^{s(x,t)} \left(\frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} \right) dz = \frac{\partial}{\partial x} \left(\int_{b(x,t)}^{s(x,t)} u dz \right) - \left[u \frac{\partial z}{\partial x} - w \right]_{b(x,t)}^{s(x,t)}.$$

Defining the depth-averaged velocity and thickness

$$\bar{u} = \frac{1}{h} \int_{b}^{s} u \, dz, \qquad h(x,t) = s(x,t) - b(x,t)$$

 and using the kinematic boundary conditions the depthaveraged mass balance becomes

$$\frac{\partial h}{\partial t} + \frac{\partial}{\partial x}(h\bar{u}) = 0.$$

• Making the shallowness approximation the normal momentum balance implies pressure p is lithostatic

$$p = \rho g(s - z) \cos \zeta$$

depth-averaging the downslope momentum balance

$$\rho \left(\frac{\partial}{\partial t} (h\overline{u}) + \frac{\partial}{\partial x} (h\overline{u^2}) \right) - \left[\rho u \left(\frac{\partial z}{\partial t} + u \frac{\partial z}{\partial x} - w \right) \right]_b^s$$

$$= \rho g h \sin \zeta + \frac{\partial}{\partial x} (h \overline{\sigma_{xx}}) - \left[\sigma_{xx} \frac{\partial z}{\partial x} - \sigma_{xz} \right]_b^s.$$

Using the kinematic and traction conditions

$$\frac{\partial}{\partial t}(h\overline{u}) + \frac{\partial}{\partial x}(\chi h\overline{u}^2) + \frac{\partial}{\partial x}\left(\frac{1}{2}gh^2\cos\zeta\right) = hgS + \frac{1}{\rho}\frac{\partial}{\partial x}\left(h\overline{\tau}_{xx}\right)$$

where the shape factor and the source terms are

$$\chi = \frac{\overline{u^2}}{\overline{u^2}} \qquad S = \cos \zeta (\tan \zeta - \mu(\overline{u}/|\overline{u}|)) - \frac{\partial b}{\partial x} \cos \zeta$$

• Usually the in-plane deviatoric stress $\overline{ au}_{xx}$ is neglected and the shape factor is assumed to be unity $\chi=1$

Equations reduce to a hyperbolic system

$$\frac{\partial h}{\partial t} + \frac{\partial}{\partial x}(h\bar{u}) = 0$$

$$\frac{\partial}{\partial t}(h\overline{u}) + \frac{\partial}{\partial x}(h\overline{u}^2) + \frac{\partial}{\partial x}\left(\frac{1}{2}gh^2\cos\zeta\right) = hgS$$

• These can be expanded and written in matrix form as

$$\frac{\partial w}{\partial t} + A \frac{\partial w}{\partial x} = gS$$

where

$$w = \begin{pmatrix} h \\ \overline{u} \end{pmatrix}, \qquad A = \begin{pmatrix} \overline{u} & h \\ g\cos\zeta & \overline{u} \end{pmatrix}, \qquad S = \begin{pmatrix} 0 \\ S \end{pmatrix}$$

• The eigenvalues of A are given by $\det(A - \lambda 1) = 0$

$$\Rightarrow (\overline{u} - \lambda)^2 - gh\cos\zeta = 0 \quad \Rightarrow \quad \lambda = \overline{u} \pm \sqrt{gh\cos\zeta}$$

• The Froude number ${\rm Fr}=\overline{u}/c$ is defined as the flow speed \overline{u} divided by the gravity wave speed $c=\sqrt{gh\cos\zeta}$

Upslope propagating granular bores

observations suggest a shock separating constants states

$$x < \xi$$
: $h(x,t) = h_1, \ \bar{u}(x,t) = \bar{u}_1,$

$$x > \xi$$
: $h(x,t) = h_2, \ \bar{u}(x,t) = \bar{u}_2,$

At shocks the mass and momentum jump conditions are

$$[h(\bar{u} - v_n)] = 0,$$

$$[h\bar{u}(\bar{u} - v_n)] + [\frac{1}{2}gh^2\cos\zeta] = 0,$$

- where v_n is the normal propagation speed and $[\![\cdot]\!]$ is the jump across the discontinuity.
- Assuming the grains come to rest after a bore

$$v_n = -\sqrt{\frac{h_1}{h_2} \left(\frac{h_1 + h_2}{2}\right) g \cos \zeta}.$$

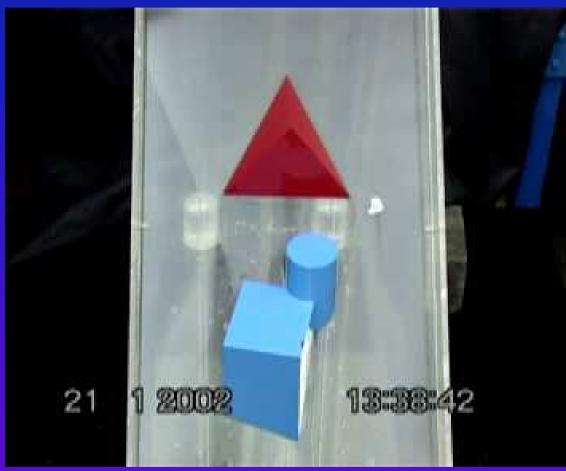
In the lab experiments

$$h_1 = 0.61 \,\mathrm{cm}, \quad h_2 = 7.29 \,\mathrm{cm} \quad \Rightarrow v_n = -16.99 \,\mathrm{cm/s}$$

• lies within 10% of the measured value of $v_n = -15.4 \, \mathrm{cm/s}$

Proposed defence for the Schneefernerhaus, Zugspitze





• Use avalanche model to compute the flow past obstacles

Two-dimensional depth-averaged system

• For avalanche thickness h and mean velocity $\bar{u} = (\bar{u}, \bar{v})$ in the downslope x and cross-slope y directions.

$$\frac{\partial h}{\partial t} + \frac{\partial}{\partial x} (h\bar{u}) + \frac{\partial}{\partial y} (h\bar{v}) = 0,$$

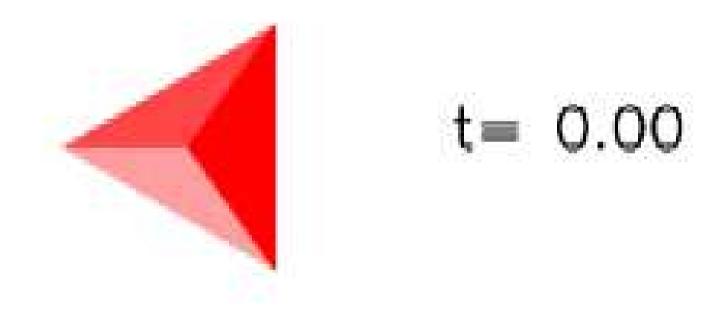
$$\frac{\partial}{\partial t} (h\bar{u}) + \frac{\partial}{\partial x} (h\bar{u}^2) + \frac{\partial}{\partial y} (h\bar{u}\bar{v}) + \frac{\partial}{\partial x} \left(\frac{1}{2}gh^2 \cos \zeta \right) = hgS_{(x)},$$

$$\frac{\partial}{\partial t} (h\bar{v}) + \frac{\partial}{\partial x} (h\bar{u}\bar{v}) + \frac{\partial}{\partial y} (h\bar{v}^2) + \frac{\partial}{\partial y} \left(\frac{1}{2}gh^2 \cos \zeta \right) = hgS_{(y)},$$

ullet source terms composed of gravity, basal friction μ and gradients of the basal topography b

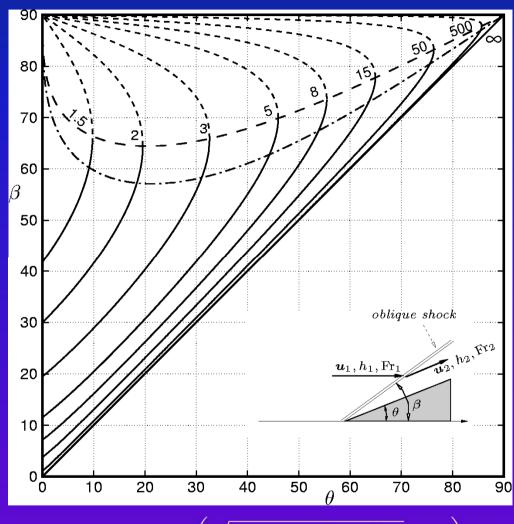
$$S_{(x)} = \sin \zeta - \mu(\bar{u}/|\bar{u}|) \cos \zeta - \frac{\partial b}{\partial x} \cos \zeta,$$

$$S_{(y)} = -\mu(\bar{v}/|\bar{u}|) \cos \zeta - \frac{\partial b}{\partial y} \cos \zeta,$$



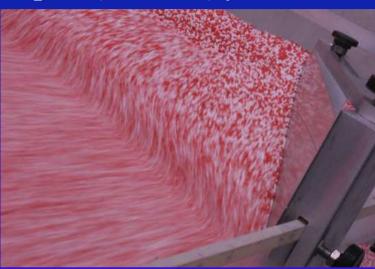
Gray, Tai & Noelle (2003) J. Fluid Mech. 491, 161-181.

Weak, strong and detached oblique shocks



$$\tan \theta = \frac{\tan \beta \left(\sqrt{1 + 8Fr_1^2 \sin^2 \beta} - 3 \right)}{2 \tan^2 \beta - 1 + \sqrt{1 + 8Fr_1^2 \sin^2 \beta}}$$

 $Fr_1 = 5, \theta = 20^{\circ}, \zeta = 38^{\circ}$



 $\beta_s = 86.2^{\circ} (78^{\circ} \pm 2^{\circ})$



$$\beta_w = 30.7^{\circ} (29^{\circ} \pm 1^{\circ})$$







Granular jets and hydraulic jumps on an inclined plane

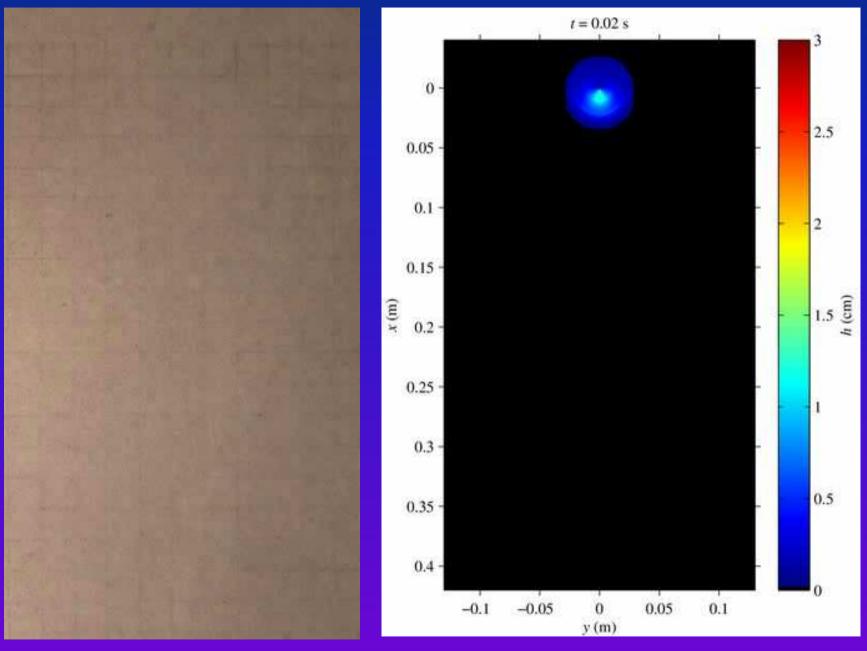
Journal of Fluid Mechanics

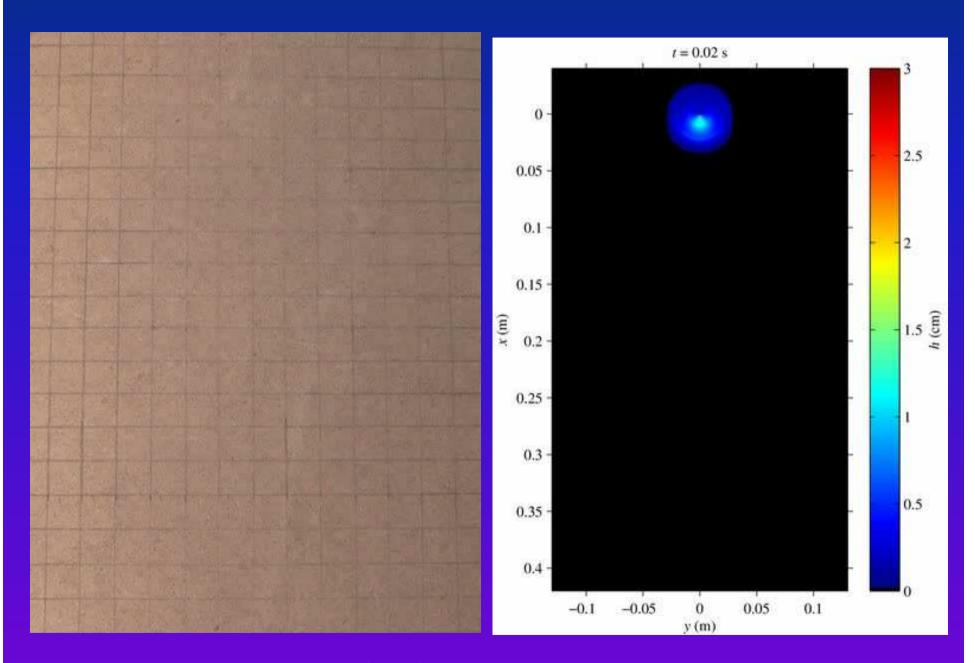
- VOLUME 675

- Oblique impingement of an inviscid jet (Hasson & Peck 1964)
- Friction law for rough beds

$$\mu = \tan \zeta_1 + \frac{\tan \zeta_2 - \tan \zeta_1}{1 + \beta h/(\mathcal{L}Fr)},$$

• including treatment of static material for $0 < Fr < \beta$ (Pouliquen & Forterre 2002)

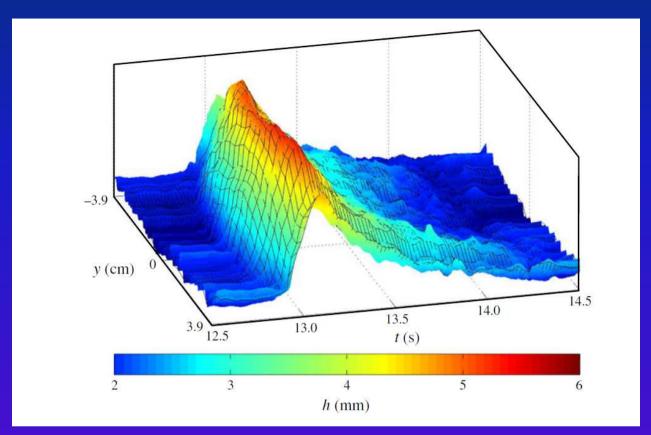




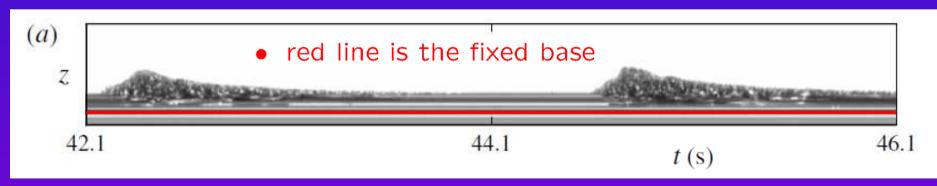
Johnson & Gray (2011) J. Fluid Mech. 675, 87-116





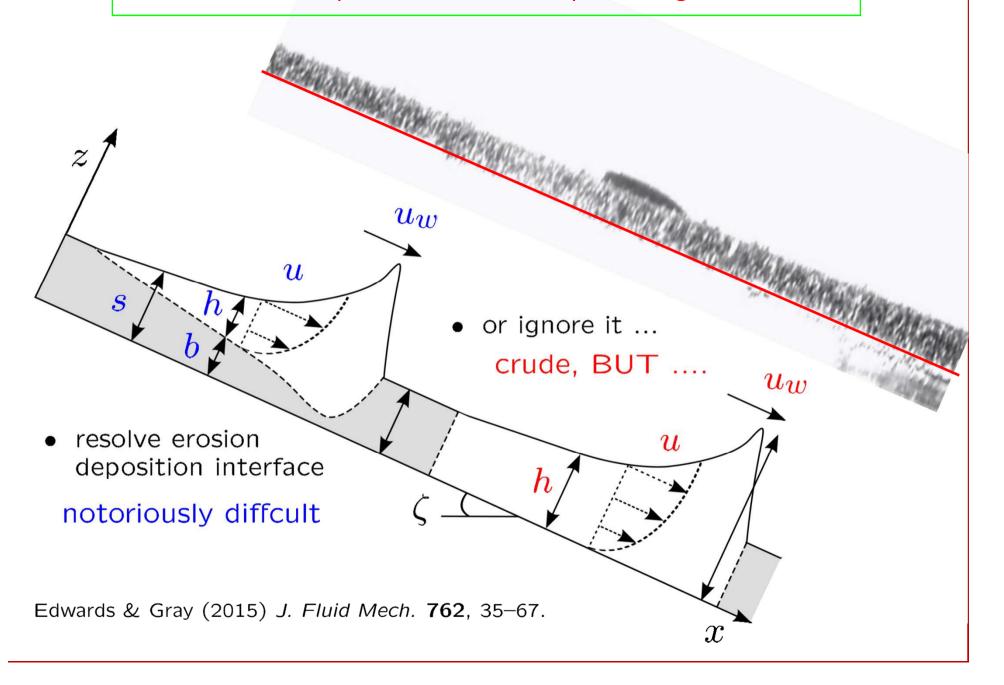


• waves are typically 5mm peak height and have 2mm stationary layer



• side-on "photo-finish" shows basal erosion and deposition

Granular solid-fluid phase transition in depth-averaged framework



Use shallow water avalanche model ...

• Uses shallow water avalanche model (e.g. Grigorian et al. 1967, Gray et al. 1999, 2003) for the thickness h and the depth-averaged velocity \bar{u}

$$\frac{\partial h}{\partial t} + \frac{\partial}{\partial x}(h\bar{u}) = 0$$

$$\frac{\partial}{\partial t}(h\bar{u}) + \frac{\partial}{\partial x}(\chi h\bar{u}^2) + \frac{\partial}{\partial x}\left(\frac{1}{2}h^2g\cos\zeta\right) = hgS$$

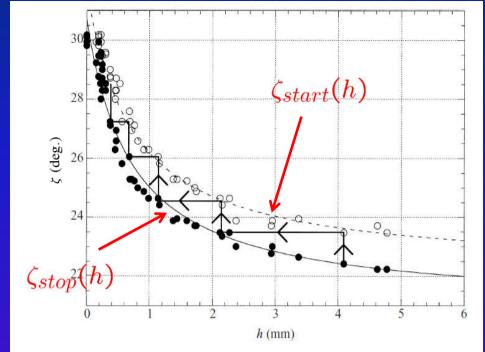
• where $\chi=\overline{u^2}/\bar{u}^2$ is the shape factor, g is the constant of gravitational acceleration and the source term

$$S = \sin \zeta - \mu \frac{\bar{u}}{|\bar{u}|} \cos \zeta$$

ullet consists of gravitational acceleration and basal fiction μ

Pouliquen & Forterre (2002)

- Measured basal friction by determining the thickness as which the grains
 - came to rest
 - when they started moving again from a static state
- gave effective basal friction law



$$\mu(h,\operatorname{Fr}) = \begin{cases} \mu_1 + \frac{\mu_2 - \mu_1}{1 + h\beta/(L\operatorname{Fr})}, & \operatorname{Fr} \geq \beta, & \operatorname{dynamic} \\ \left(\frac{\operatorname{Fr}}{\beta}\right)^{\kappa} (\mu_1 - \mu_3) + \mu_3 + \frac{\mu_2 - \mu_1}{1 + h/L}, & 0 < \operatorname{Fr} < \beta, & \operatorname{intermediate} \\ \mu_3 + \frac{\mu_2 - \mu_1}{1 + h/L}, & \operatorname{Fr} = 0, & \operatorname{static} \end{cases}$$

• where Fr is the Froude number, $\kappa = 10^{-3}$ and $\mu_1 = \tan \zeta_1$, $\mu_2 = \tan \zeta_2$ and $\mu_3 = \tan \zeta_3$ are the tangents of the angles, ζ_1 , ζ_2 and ζ_3 .

Pouliquen & Forterre (2002) J. Fluid Mech. 453, 133-151.

Travelling-wave solutions in the absence of viscosity

ullet In a frame travelling at speed u_w with coordinates

$$\xi = x - u_w t, \qquad \tau = t.$$

• Assuming $\partial/\partial \tau = 0$ and $\chi = 1$ the system reduces to

$$rac{\mathsf{d}}{\mathsf{d}\xi} ig(h(ar{u} - u_w) ig) = \mathsf{0},$$

$$h(\bar{u} - u_w)\frac{\mathrm{d}\bar{u}}{\mathrm{d}\xi} + hg\cos\zeta\frac{\mathrm{d}h}{\mathrm{d}\xi} = hg\cos\zeta(\tan\zeta - \mu)$$

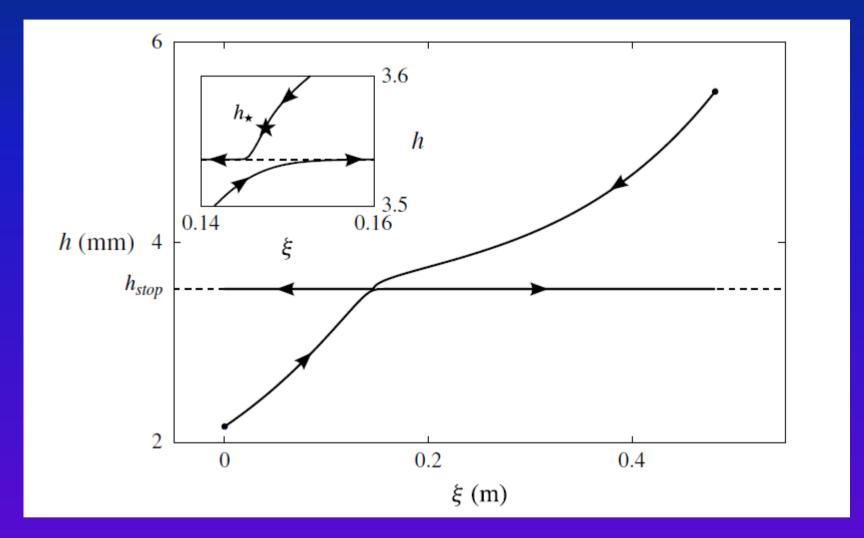
• Since $\bar{u}=0$ in a stationary layer of thickness $h=h_+$

$$h(\bar{u}-u_w)=-h_+u_w \qquad \Rightarrow \qquad \bar{u}=u_w\left(1-\frac{h_+}{h}\right).$$

• The flow thickness for which $Fr = \beta$ is now defined as $h = h_{\star}$

$$\Rightarrow \qquad u_w = \frac{\beta h_{\star}^{3/2} \sqrt{g \cos \zeta}}{h_{\star} - h_{+}}.$$

Edwards & Gray (2015) J. Fluid Mech. 762, 35-67.



- Integration of the first order ODE indicates a problem
- ullet solution asymptotes to a critical thickness $h_*\gg h_{crit}>h_{stop}$
- To get through this point, ones needs a little bit of viscosity

The $\mu(I)$ -rheology for liquid-like granular flows

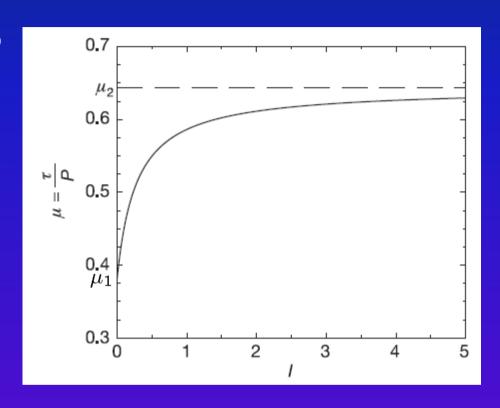
• GDR MIDI (2004) and Jop et al. (2006): proposed constitutive law

$$\tau = \mu(I)p\frac{D}{||D||}$$

where 2nd invariant

$$||\boldsymbol{D}|| = \sqrt{\frac{1}{2} \text{tr} \boldsymbol{D}^2}$$

• If $\mu = \text{const}$ this reduces to Mohr-Coulomb law



ullet BUT, friction μ is a function of the inertial number I

$$\mu(I) = \mu_1 + \frac{\mu_2 - \mu_1}{I_0/I + 1}, \qquad I = \frac{2||\boldsymbol{D}||d}{\sqrt{p/\rho^*}}$$

• where d is the particle diameter and ρ^* is the intrinsic density.

The Continuum Sand-Glass

Solver: We apply the Open-source Gerris (Popinet 2003)

http://gfs.sourceforge.net

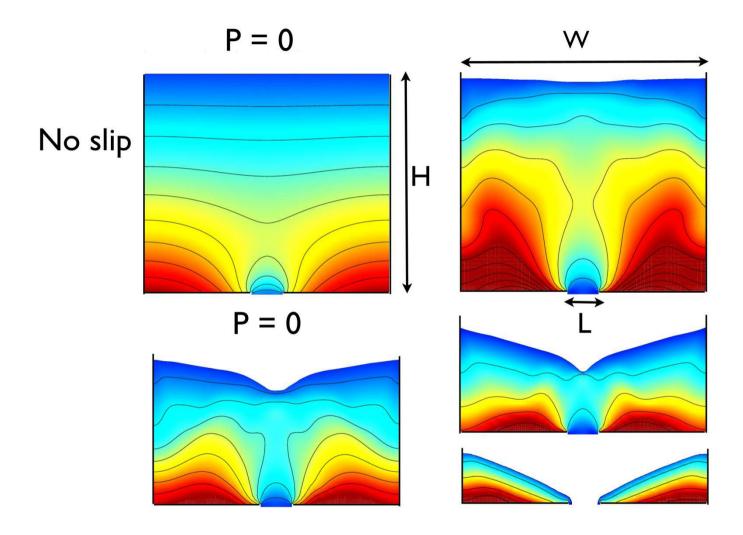
(incompressible Navier-Stokes equations using a VOF method) (Popinet 2003, 2009)

$$\begin{array}{rcl} \boldsymbol{\nabla}.\boldsymbol{u} &=& 0 \\ \rho\left(\frac{\partial\boldsymbol{u}}{\partial t}+\boldsymbol{u}.\boldsymbol{\nabla}\boldsymbol{u}\right) &=& -\boldsymbol{\nabla}p+\boldsymbol{\nabla}.(2\eta\boldsymbol{D})+\rho\boldsymbol{g} \\ \frac{\partial c}{\partial t}+\boldsymbol{\nabla}.(c\boldsymbol{u}) &=& 0 \\ \rho &=& c\;\rho_{\mathsf{air}}\;+\;(1-c)\;\rho_{\mathsf{grains}} \\ \eta &=& c\;\eta_{\mathsf{air}}\;+\;(1-c)\;\eta_{\mathsf{grains}} \end{array}$$

- \Rightarrow We chose $\rho_{\rm air} << \rho_{\rm grains}$
- \Rightarrow The free surface is solved in the course of time
- ⇒ We implement the viscosity:

$$\eta_{\mathrm{grains}} = \min\left(rac{\mu P}{|\dot{\gamma}|}, \eta_{max}
ight),$$

The Continuum Sand-Glass



We chose the following value for the rheological parameters:

$$\mu_s = 0.32$$
, $\mu_d = 0.60$, $I_0 = 0.4$

The Bagnold solution

• For steady-uniform flow u=(u(z),0,0) the normal and downslope momentum balances imply that

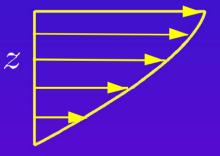
$$p = \rho g(h - z) \cos \zeta,$$
 $\tau_{xz} = \rho g(h - z) \sin \zeta$

• Rheology then implies $\mu(I) = \tan \zeta$ and hence I is equal to a constant

$$I_{\zeta} = I_0 \left(\frac{\tan \zeta - \tan \zeta_1}{\tan \zeta_2 - \tan \zeta} \right)$$

Solve I equation for the downslope velocity

$$u = \frac{2I_{\zeta}}{3d} \sqrt{\Phi g \cos \zeta} \left(h^{3/2} - (h-z)^{3/2} \right).$$



u

The depth-averaged Bagnold velocity satisfies

$$\bar{u} = \frac{2I_{\zeta}}{5d} \sqrt{\Phi g \cos \zeta} \ h^{3/2}$$

The depth-averaged $\mu(I)$ -rheology for granular flows

 To first order the inviscid avalanche equations emerge naturally with the dynamic basal friction law

$$\mu_b(h, Fr) = \mu_1 + \frac{\mu_2 - \mu_1}{\beta h/(LFr) + 1}, \qquad Fr > \beta,$$

This is just Pouliquen & Forterre's (2002) law, where

$$\mathsf{Fr} = rac{|ar{u}|}{\sqrt{gh\cos\zeta}}$$

Now add in the in-plane deviatoric stress

$$\tau_{xx} = \mu(I)p\frac{D_{xx}}{||\boldsymbol{D}||}$$

Assume shallow and use Bagnold solution to evaluate

$$D_{xx} = \frac{\partial u}{\partial x}, \qquad ||D|| = \frac{1}{2} \left| \frac{\partial u}{\partial z} \right|$$

• the in-plane deviatoric stress is

$$au_{xx} = 2
ho g \sin\zeta \left(h^{1/2}(h-z)^{1/2} - (h-z)\right) rac{\partial h}{\partial x}.$$

formal depth-integration gives

$$h\bar{\tau}_{xx} = \frac{1}{3}\rho g \sin\zeta \, h^2 \frac{\partial h}{\partial x}.$$

Use Bagnold velocity to reformulate

$$h\bar{\tau}_{xx} = \rho\nu h^{3/2} \frac{\partial \bar{u}}{\partial x}$$

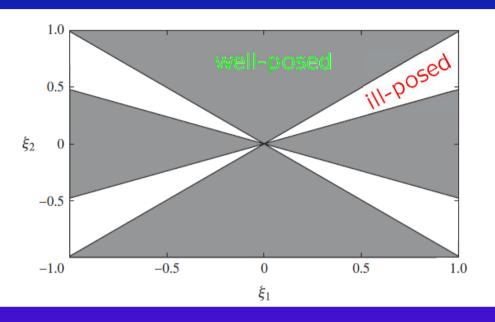
where

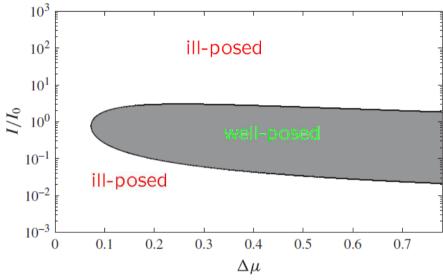
$$\nu = \frac{2L\sqrt{g}}{9\beta} \frac{\sin\zeta}{\sqrt{\cos\zeta}} \left(\frac{\tan\zeta_2 - \tan\zeta}{\tan\zeta - \tan\zeta_1} \right).$$

negative and ill-posed outside range of steady uniform flow

ullet Full $\mu(I)$ -rheology ill-posed for high and low inertial numbers

Barker et al. (2015) J. Fluid Mech. 779, 794-818.





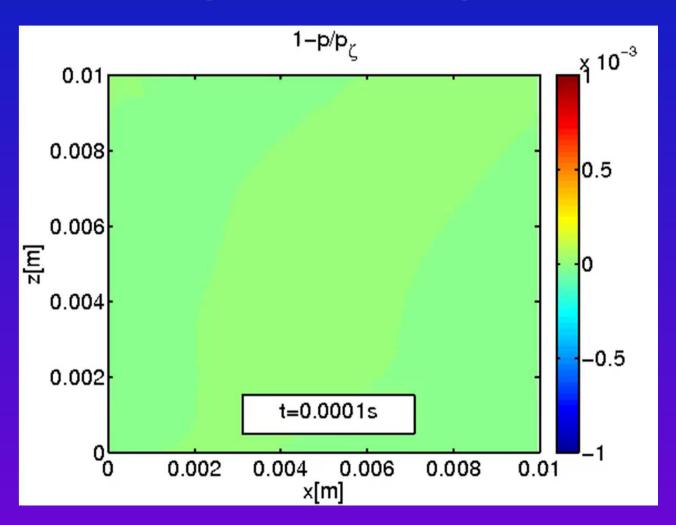
• Small perturbations will grow infinitely quickly in the high wave number limit for certain wave vectors (ξ_1, ξ_2)

$$\begin{bmatrix} \hat{\boldsymbol{u}}(\boldsymbol{x},t) \\ \hat{p}(\boldsymbol{x},t) \end{bmatrix} = \exp\left(i\boldsymbol{\xi}\cdot\boldsymbol{x} + \lambda t\right) \begin{bmatrix} \tilde{\boldsymbol{u}} \\ \tilde{p} \end{bmatrix}$$

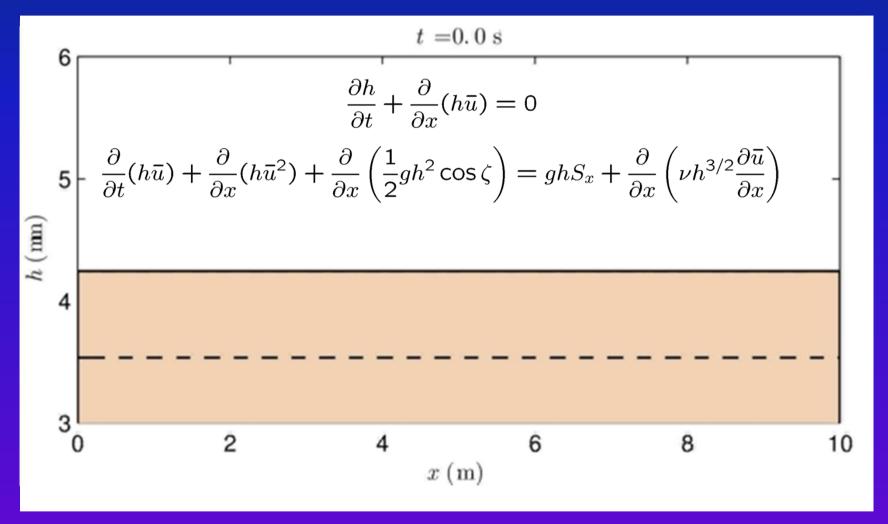
$$\mu(I) = \mu_1 + \frac{\Delta \mu}{I_0/I + 1}$$

$$I = \frac{2||D||d}{\sqrt{p/\rho^*}}$$

- PRACTICAL IMPLICATION: Two-dimensional transient computations will blow-up in the ill-posed region of parameter space
- In this case for Bagnold flow in the high inertial number regime

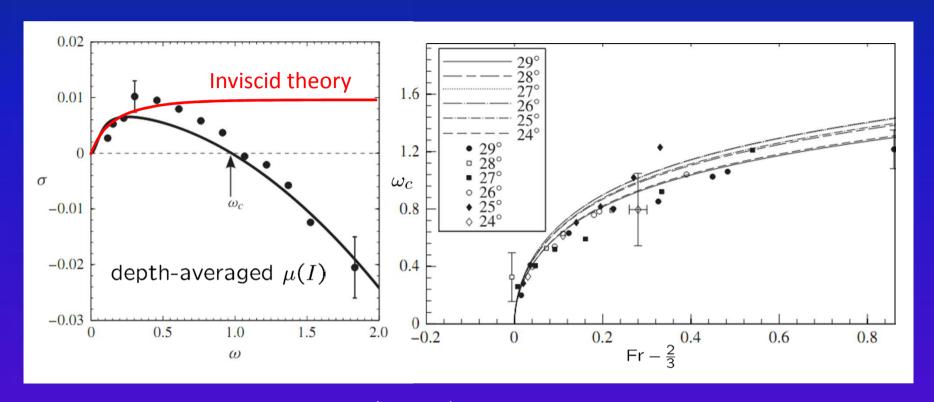


Application of depth-averaged theory to granular roll-waves



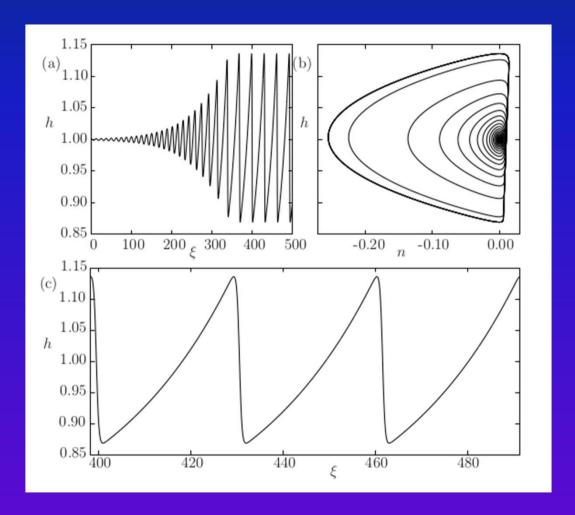
- Adds a singular perturbation to the momentum equation
- ullet This is the only form that is not singular in h or ar u

Measurements of the spatial growth rate of granular roll-waves



- Forterre & Pouliquen (2003) used loudspeaker to initiate roll waves of a given frequency
- Inviscid theory predicts critical Froude ${\rm Fr}_c=2/3$, but growth occurs at all frequencies ω
- Depth-averaged rheology predicts the cut-off frequency ω_c
- MATCHES WITHOUT ANY FITTING PARAMETERS

Exact travelling wave solutions for roll waves

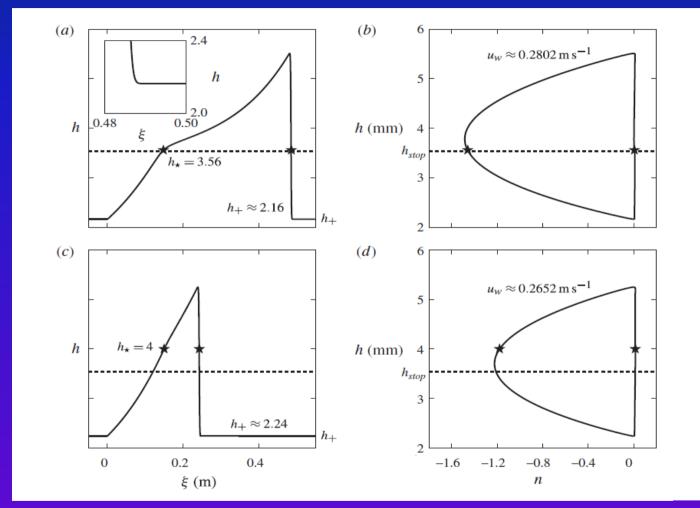


$$n = \frac{dh}{d\xi}$$

• computed by numerically integrating 2nd order ODE with prescribed Fr and u_w until a limit cycle is formed

Gray & Edwards (2014) J. Fluid Mech. 755, 503-534.

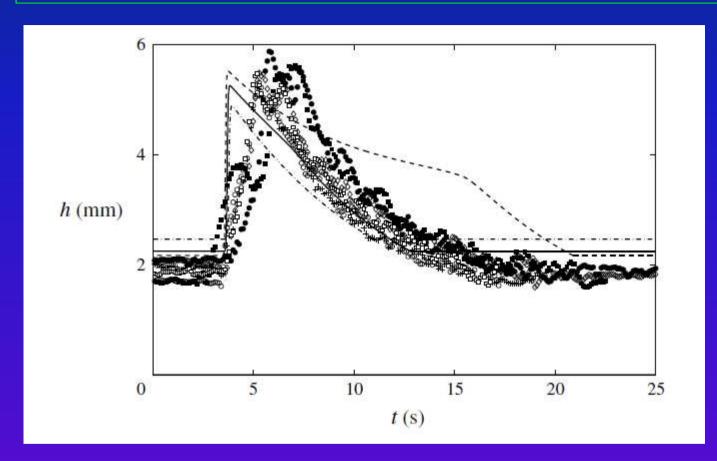
Exact travelling wave solutions for erosion-deposition waves



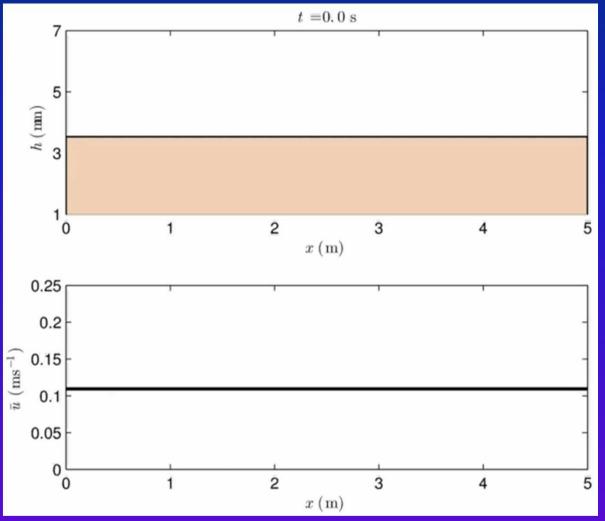
$$n = \frac{dh}{d\xi}$$

- For each solution h_+ and h_* must be prescribed.
- viscosity allows solution to cross the critical line!

Exact travelling wave solutions for erosion-deposition waves



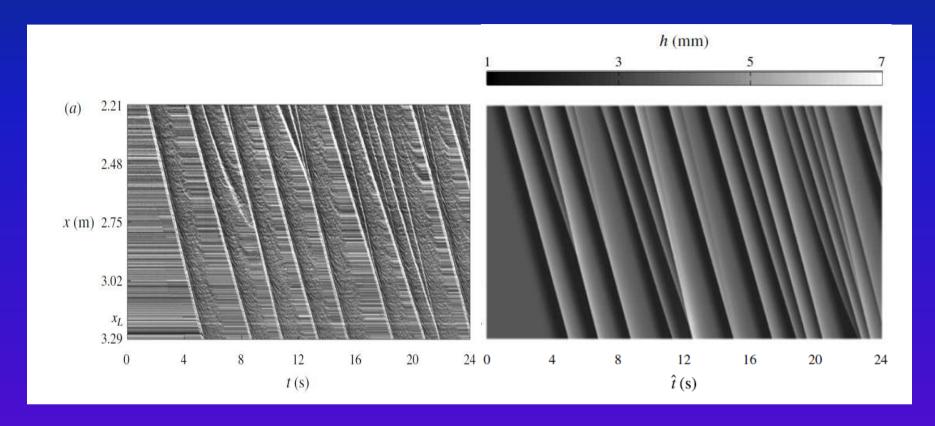
- Exact solution picks off the correct amplitude and wavelength
- ALTHOUGH its shape is a little different
- MAJOR STEP FORWARD in modelling erosion-deposition problems with shallow erodible layers





- Numerical solutions with random noise rapidly coarsen into large amplitude waves
- Close to stopping very destructive waves are formed!

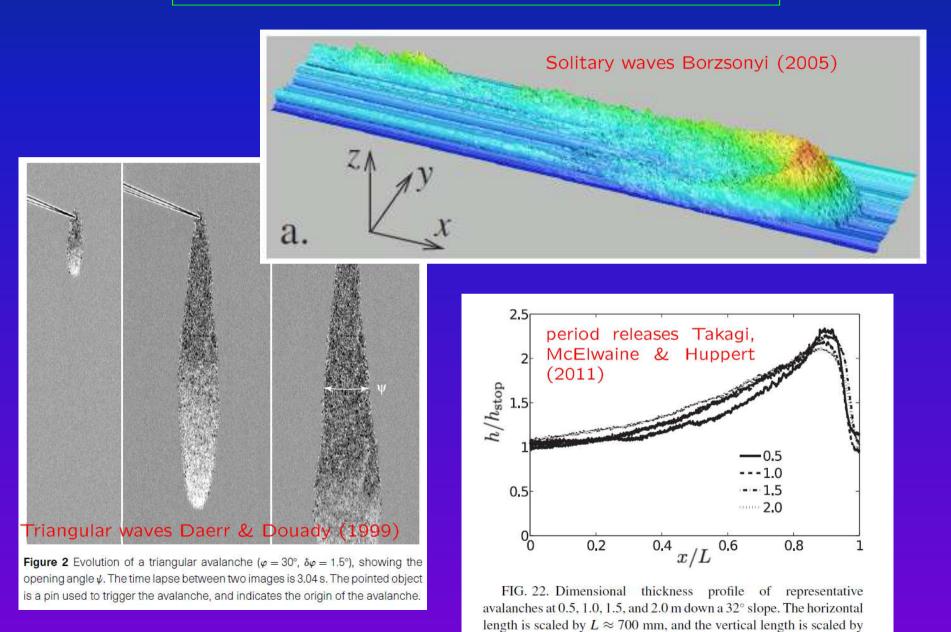
Complex coarsening dynamics is qualitatively reproduced



- Experimental space-time plot shows:-
 - regions of stationary material as horizontal straight lines
 - the wave-fronts as white lines
- very similar in computations (right)

Edwards & Gray (2015) *J. Fluid Mech.* **762**, 35-67. Razis, Edwards, Gray & van der Weele (2014) *Phys. Fluids* **26**, 123305.

Theory has the potential to explain other situations ...



~ 1.5 mm. The mean profiles almost overlan suggesting that

... and for segregation-induced fingering instabilities

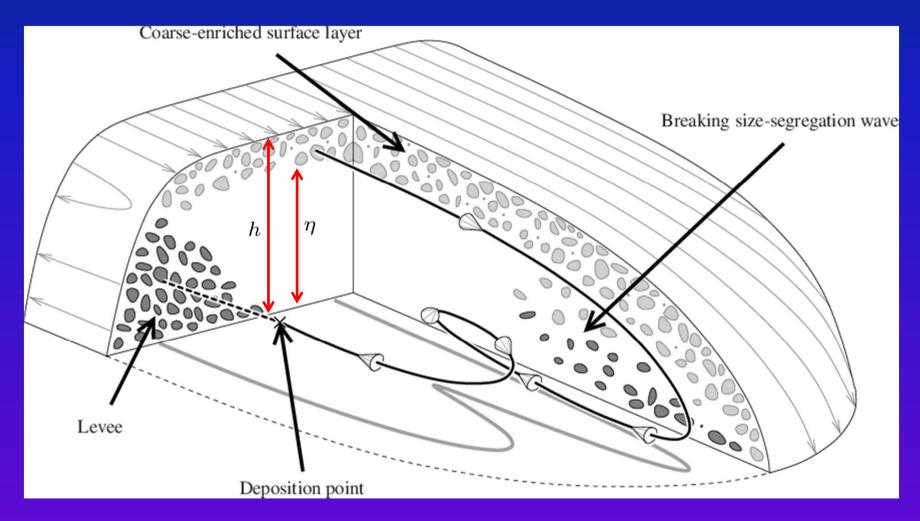


Pouliquen, Delours & Savage (1997), Nature. **386**, 816-817. Woodhouse *et al.* (2012), J. Fluid Mech. **709**, 543-580.

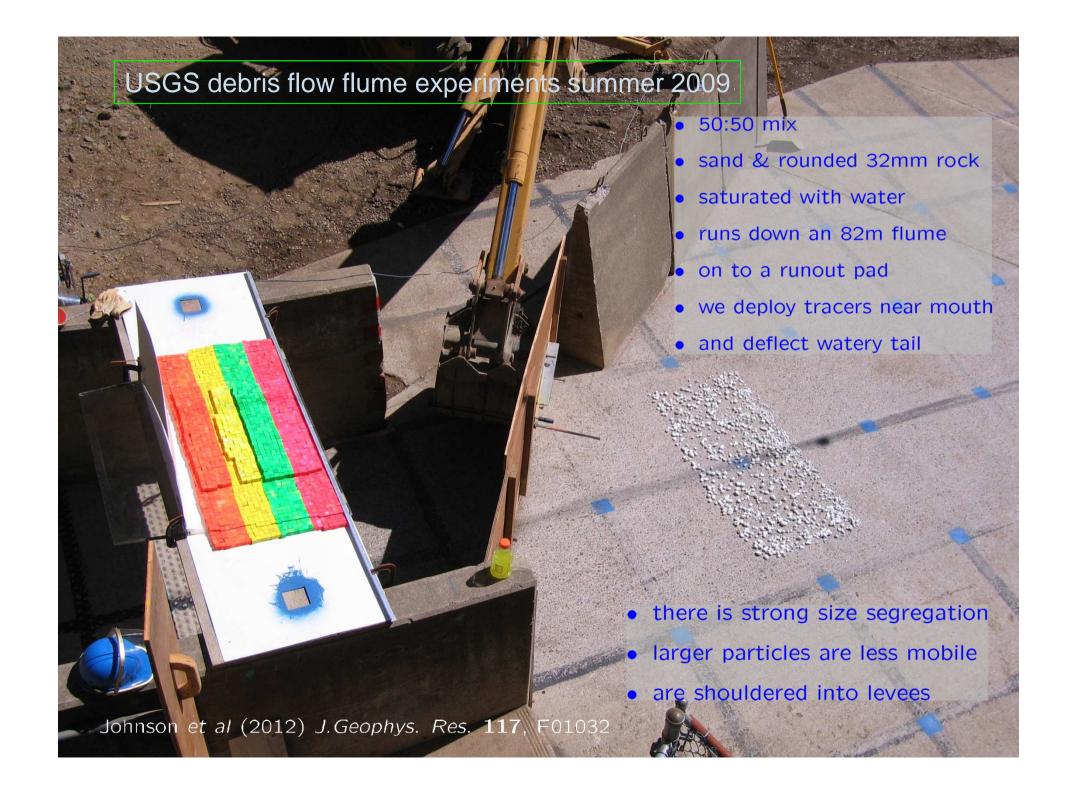


Kokelaar et al (2014) Earth Planet. Sci. Lett. 385, 172-180.

Schematic diagram for the levee formation process



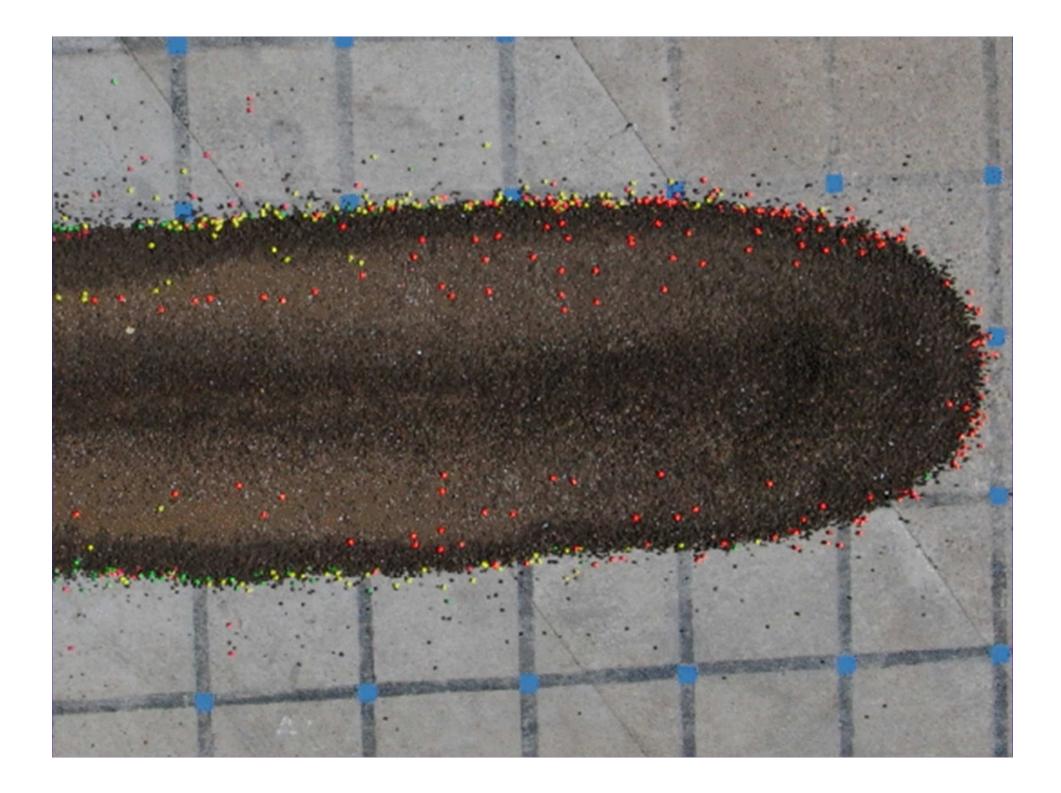
- larger particles are shouldered to the sides to create levees
- this is an example of a segregation-mobility feedback effect



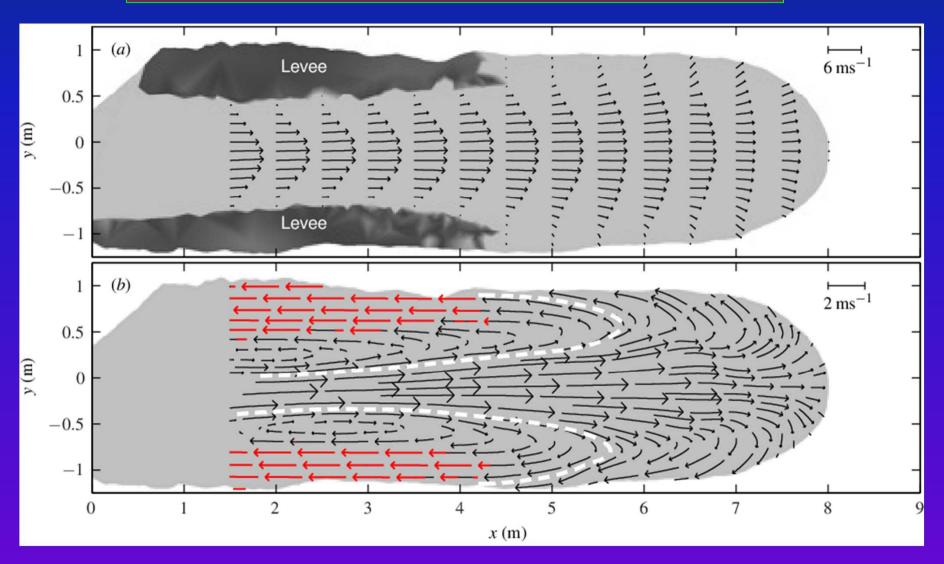








Surface velocity in stationary and front centred frames



ullet Oxyz are the downslope, cross-slope and normal directions

A simple kinematic model for 3D velocity field in the moving frame

• Bulk velocity $\mathbf{u} = (u, v, w)$ is assumed to be incompressible

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

• Integrating through the avalanche depth h

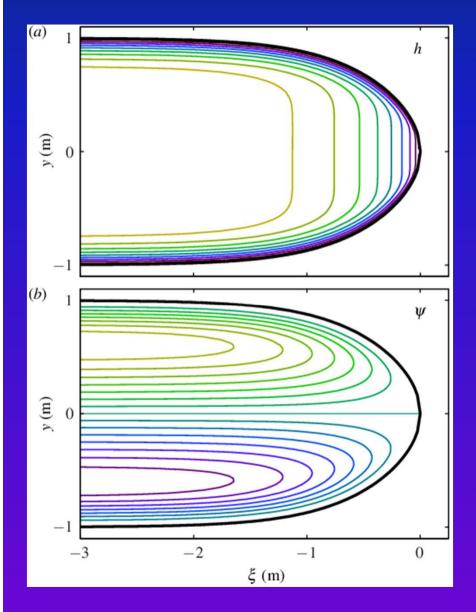
$$\frac{\partial h}{\partial t} + \frac{\partial}{\partial x} (h\bar{u}) + \frac{\partial}{\partial y} (h\bar{v}) = 0$$

where the depth-averaged velocity

$$\bar{u} = \frac{1}{h} \int_0^h u \, dz, \qquad \bar{v} = \frac{1}{h} \int_0^h v \, dz$$

• In frame $\xi = x - u_F t$ the bulk flow is steady

$$\frac{\partial}{\partial \xi} \left(h \left(\bar{u} - u_F \right) \right) + \frac{\partial}{\partial y} \left(h \bar{v} \right) = 0$$



define a streamfunction

$$\frac{\partial \psi}{\partial y} = h(\bar{u} - u_F), \quad \frac{\partial \psi}{\partial \xi} = -h\bar{v}$$

empirical front shape

$$y_0(\xi) = W\sqrt{\tanh\left(-\frac{\xi}{W}\right)}$$

• self similar thickness h

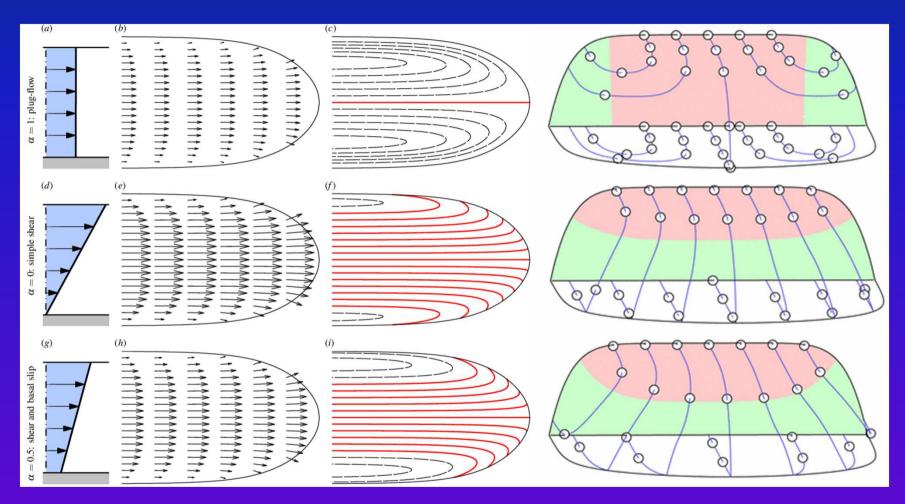
$$h(y_0, y) = \frac{H}{W} \left(\frac{y_0^{2n} - y^{2n}}{y_0^{2n-1}} \right)$$

recirculating streamfunction

$$\psi(\xi,y) = \psi(y_0,y)$$

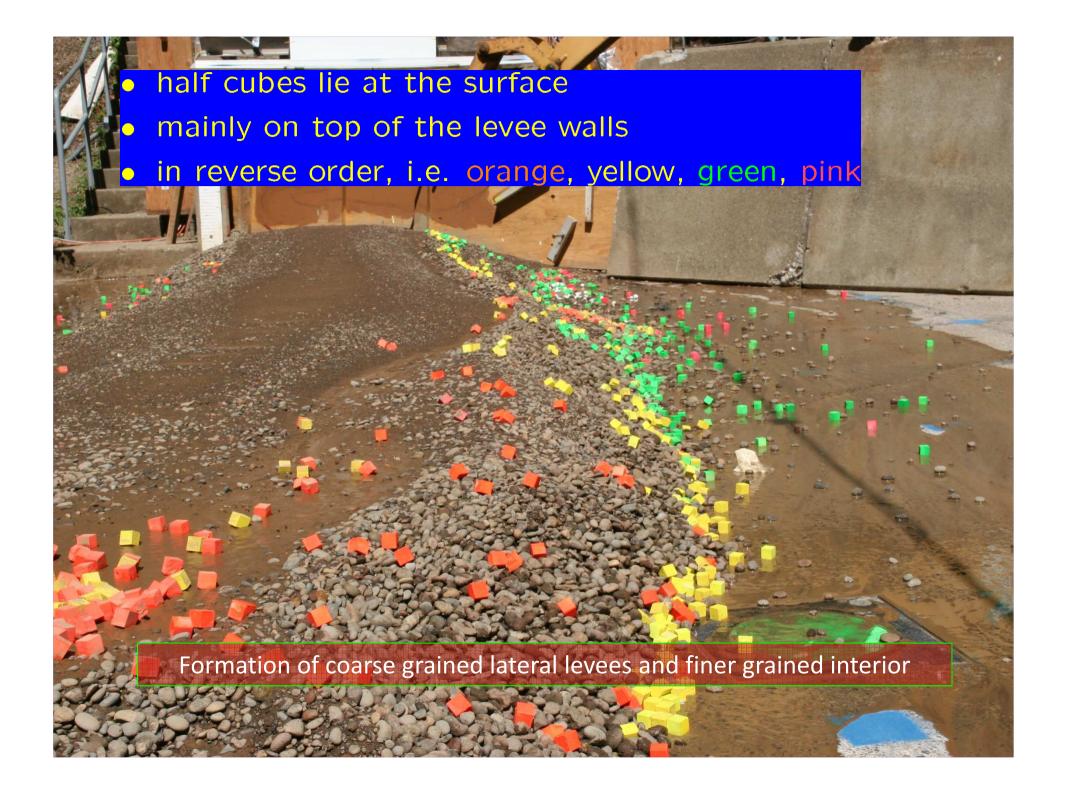
to approximate the flow

Reconstruction of the 3D velocity field

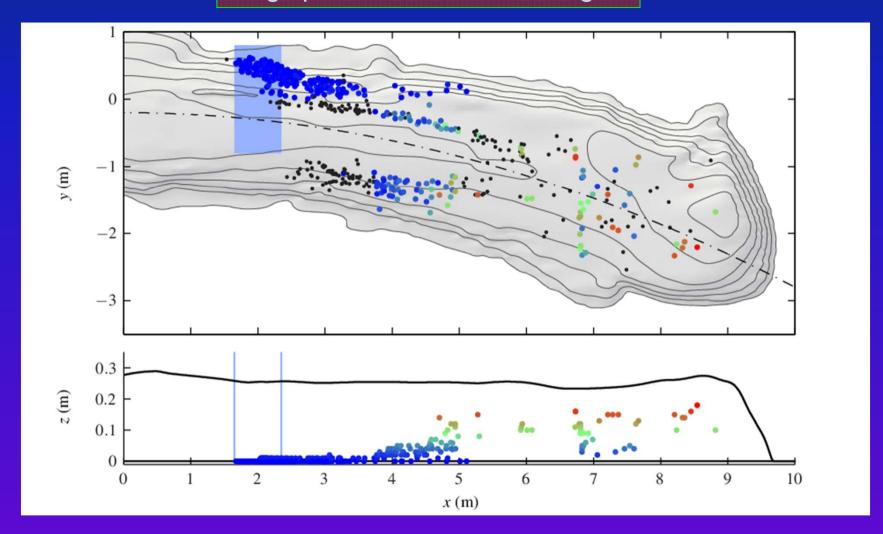


assuming linear velocity profles with depth z

$$(u,v) = \left(\alpha + 2(1-\alpha)\frac{z}{h}\right)(\bar{u},\bar{v})$$



Large particle tracer stone heights



- Strong evidence for size segregation and recirculation
- BUT, stones never rise to the free surface again



