

	 Content Introduction: How to make powders and granules Type of industries, typical size of granulators Continuous granulation Current 'art' Cases of control (-Case of aspertame) State-of-the-Art in industrial processes Future of control of these granulators
	-Will high shear granulation survive the next decades?
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Liquid to Powder	Liquid to Agglomerate	Powder to Agglomerate
(LP)	(LA)	(PA)
 Spray drying Flash drying 	•Multi stage drying •Filtermat •Fluid bed agglomeration •AGT •Procell •Cont. fluid bed aggl. •Fluid bed coating •Pan coating •Drum coating •(Prilling)	 Low shear granulation Pan and drum granulation Low-medium shear granulation High Shear granulation High Shear granulation High bed granulation Fluid bed granulation Belletising Briquetting Tabletting (Sintering)





Typical size of granulators

Pharmaceutical: 5-200 litres

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- Food and food additives: 20-5000 liters
- Waste handling industries: 0.1-100 T/day
- Fertiliser industries 10-1000 T/day
- Detergent industries: 0.1-10 T/day









	Sizes:			
	Model	Volume	Throughput	Dimensions
		[Liter]	[approx, t/h]	L x W x H [mm]
	KM 150 D	150	4.5	2 x 1
	KM 300 D	300	9	3 x 1
	KM 600 D	600	18	4 x 1.5
- J. S.	KM 1200 D	1200	36	4 x 1.5
Para Part State	KM 2000 D	2000	60	5 x 1.5
	KM 3000 D	3000	90	6 x 1.5
	KM 4200 D	4200	126	7 x 2
	KM 6000 D	6000	180	8 x 2.5
	KM 8000 D	8000	240	8 x 2,5
	KM 10000 D	10000	300	9 x 3
	KM 13500 D	13500	405	10 x 3
	KM 15000 D	15000	450	11 x 3
KM 1200 D	KM 20000 D	20000	600	12 x 3
Kivi 1200 D	KM 30000 D	30000	900	14 × 3 5













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CFWS1 last year we had different outputs. Constantijn Sanders; 11-6-2007



















	What is the current state of the art
	 Circuits are controlled by experienced operators
	 Model for granulator is available, but mostly developed in house
	 On-line analysis is not yet available, except for psd measurements
	 Sensors for psd available, the rest still difficult
	 Population balances for feed forward control is developed now
	 Expert systems are being tested
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	Modeling - approach	
	 predict outlet conditions: temperatures, moisture contents, psd validation using pilot plant experiments assumptions correction factors: particle rotation (gas-particles) heat from the wall (oil-particles) influence of rotor fitted from experiments use residence time experiments to describe particle motion 	
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